

## Potential Energy Approach -

The general expression for potential energy is given by -

$$PE = (U - W_{ext})$$

[The strain energy density function is the negative of the work done (per unit vol) by the internal forces in an elastic body through the displacements i.e. Thus because the sum of internal forces is Consave, it is equal to the work these forces would perform in returning to the unstrained position]

$$J_L = \frac{1}{2} \int \sigma^T e \cdot A \cdot d\mathbf{x} - \int u^T f \cdot A \cdot d\mathbf{x} - \int u^T T \cdot d\mathbf{x}$$

~~$\int u^T \sigma \cdot d\mathbf{x} - \sum_i u_i p_i$~~

$\sigma \rightarrow$  Stress,  $e \rightarrow$  Strain,  $A \rightarrow$  Area,  $u \rightarrow$  Displacement.  
 $f \rightarrow$  body force,  $T \rightarrow$  traction force,  $p \rightarrow$  Point load.

When the Continuum has been discretized into finite elements, the expression for  $J_L$  becomes.

$$J_L = \sum_e \frac{1}{2} \int \sigma^T e A d\mathbf{x} - \sum_e \int u^T T \cdot d\mathbf{x} - \sum_e \int u^T f \cdot A d\mathbf{x} - \sum_i Q_i p_i$$

The above equation can be written as

$$\underline{J_L} = \sum_e u_e - \sum_e \int u^T f \cdot A \cdot d\mathbf{x} - \sum_e \int u^T T \cdot d\mathbf{x} - \sum_i Q_i p_i$$

Strain energy  $U_e = \frac{1}{2} \int \sigma^T e A \cdot d\mathbf{x}$

Stiffness matrix for a bar element.

$$u_e = \frac{1}{2} \int \sigma^T e A \cdot d\mathbf{x}$$

$$= \frac{1}{2} \int (EBu)^T (Bu) \cdot A \cdot d\mathbf{x}$$

$$e = Bu$$

$$G = Ee = EBu$$

$$= \frac{1}{2} \int E B^T U^T B U A \cdot d\alpha = \frac{1}{2} U^T [A \in B^T B U \{d\alpha\}]$$

$$= \frac{1}{2} U^T [A \in B^T B U \cdot 1]$$

$$[B] = \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix}, \quad B^T = \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \end{bmatrix}$$

$$U_e = \frac{1}{2} U^T A E \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \end{bmatrix} \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \cdot u \cdot 1$$

$$= \frac{1}{2} U^T A E \times \frac{1}{2} \begin{bmatrix} -1 \\ 1 \end{bmatrix} \times \frac{1}{2} \begin{bmatrix} -1 & 1 \end{bmatrix} \cdot u \cdot 1$$

$$= \frac{1}{2} U^T A E \times \frac{1}{4} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \cdot u \cancel{\times 1}$$

$$= \frac{1}{2} U^T \frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} u$$

The above eqn is of the form.

$$U_e = \frac{1}{2} U^T \cdot [\kappa] \cdot u$$

$$\therefore [\kappa] = \frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

work done = strain energy (p)

$$\begin{aligned}
 &= \frac{1}{2} \{w\}^T \{w^*\} \\
 &= \frac{1}{2} \{[u]\} \{w^*\}^T \{w\} \\
 &= \frac{1}{2} \{w^*\}^T \{u\} \{w\}
 \end{aligned}$$